Windows 10 IoT Enterprise LTSC 2021 (21H2) User Manual

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www.moxa.com/products



Windows 10 IoT Enterprise LTSC 2021 (21H2) User Manual

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1. Introduction

This Windows 10 IoT Enterprise LTSC 2021 (21H2) user manual is applicable to Moxa's x86-based computers listed below and covers the complete set of instructions for these series. Detailed instructions on configuring advanced settings are covered in following chapters of the manual. Before referring to sections in these chapters, confirm that the hardware specification of your computer model supports the functions/settings covered therein.

Applicable Series

- DA-681C Series
- DA-682C Series
- DA-820C Series
- V2403C Series
- V2406C Series
- MC-1200 Series
- MC-3201 Series

Moxa Windows

Moxa computers are integrated with Windows drivers and I/O controller utilities based on the Microsoft Windows up-to-date version so that you can use the most compatible hardware-software combination in your application field.

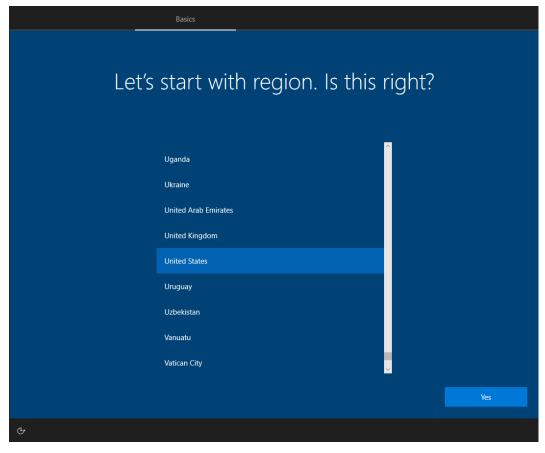
2. System Initialization

In this chapter, we describe how to initialize the system settings when you boot up the computer for the first time. When you turn on the computer, you will see the Windows Out of Box Experience (OOBE) wizard. OOBE consists of a series of screens that require customers to accept the license agreement, connect to the internet, log in with or sign up for a Microsoft Account, and share information with the OEM.

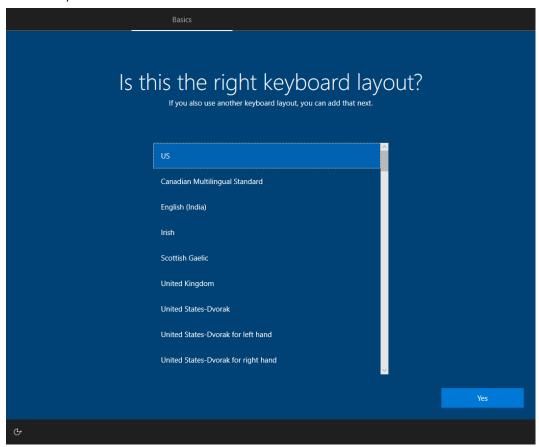
Initializing User Settings

The following is a non-exhaustive list of OOBE screens that you will see in the order that they are listed here:

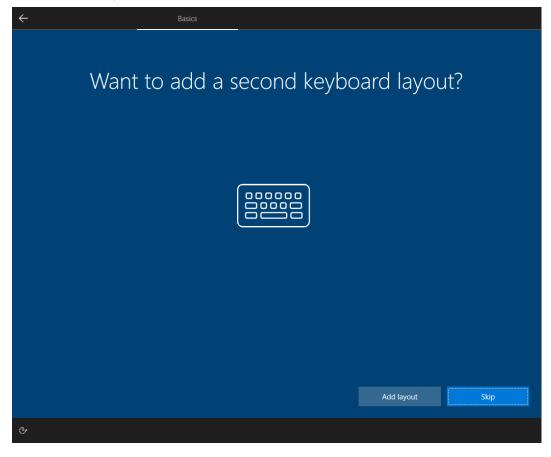
1. Select a region.



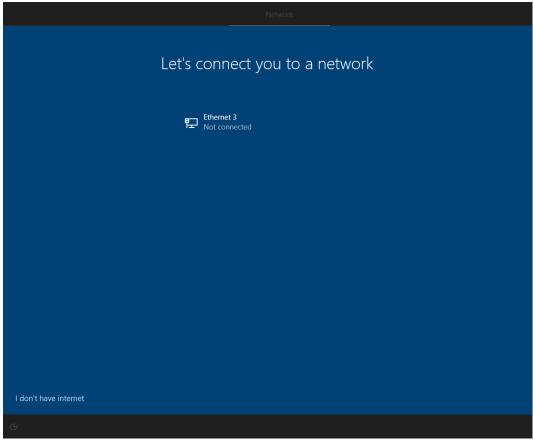
2. Select a keyboard.

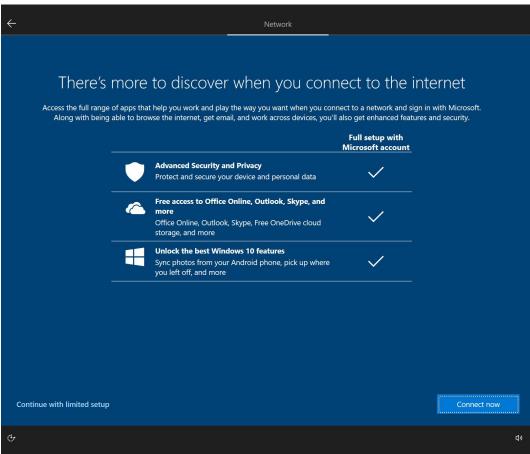


3. Select a second keyboard.

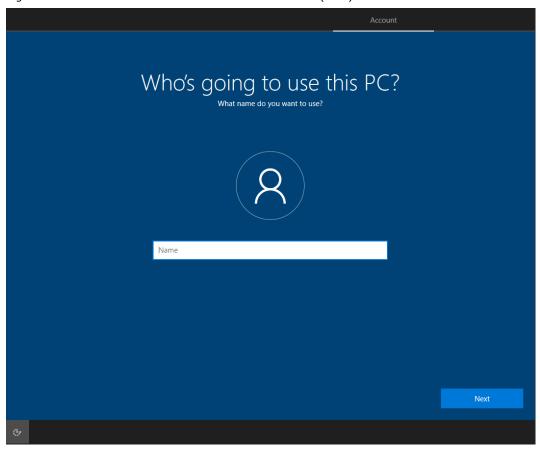


4. Connect to a network or continue with limited setup.

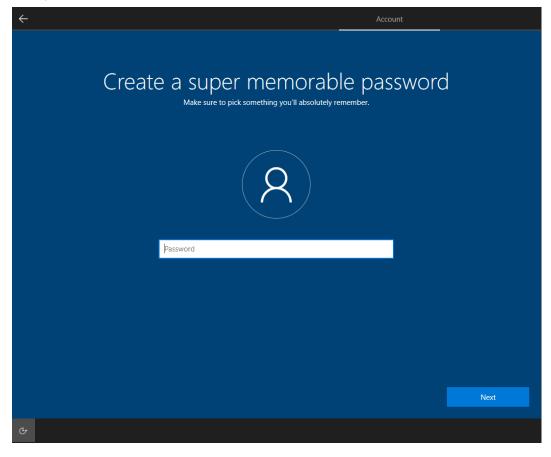




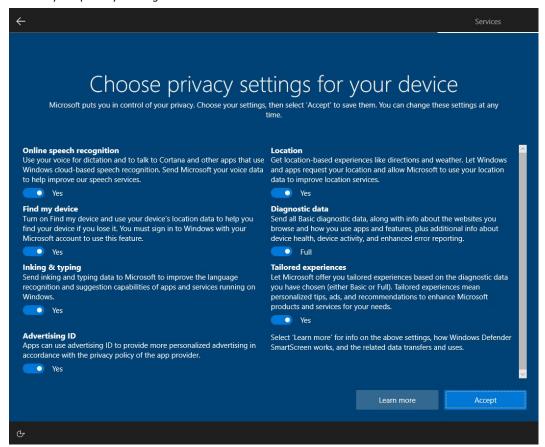
5. Sign in to or create a local account or a Microsoft account (MSA).



6. Set a password.



7. Choose your privacy settings.



Initializing the System

After the OOBE settings, you will be redirected to the device desktop of the device. Wait until the process is complete.

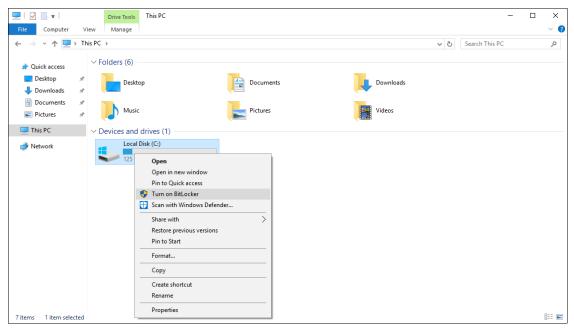


After the process is completed, the system initialization is done. The device will reboot, and the new settings will take effect after the system restarts.

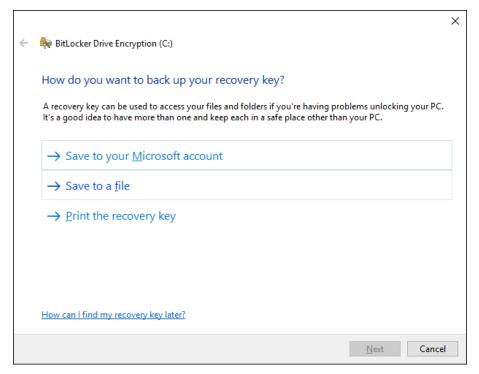
This chapter describes the BitLocker setup process.

Enabling the BitLocker

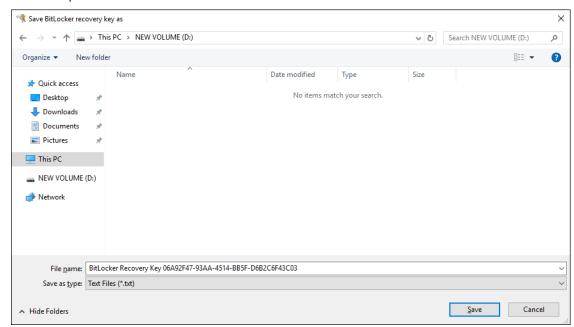
1. In the Windows Devices and drives, right-click on the drive and select Turn on BitLocker.



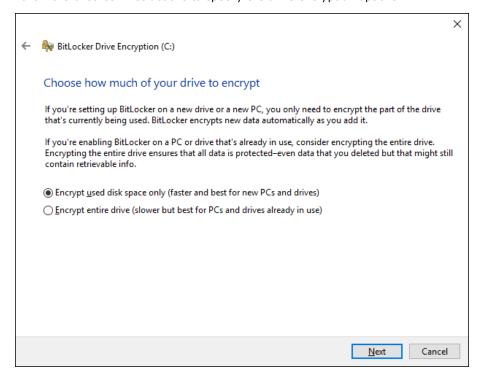
2. Select an option to back up the recovery key. For example, select **Save to a file**.

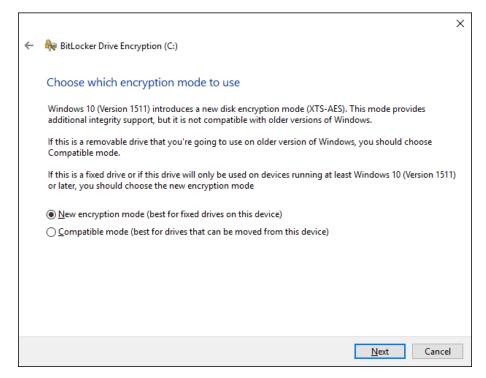


3. Select the path to store the file in.

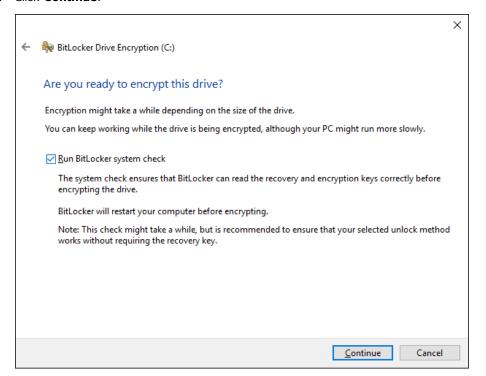


4. Follow the onscreen instructions to specify the drive encryption options.





5. Click Continue.



6. Restart the computer.

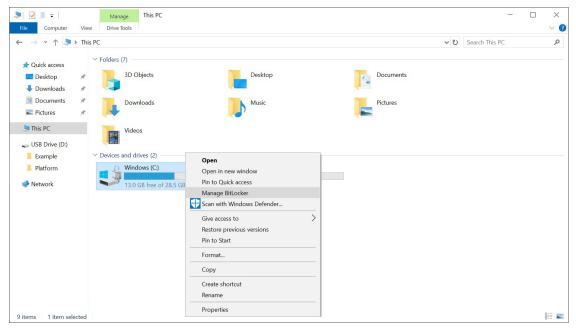


7. Wait for the encryption process to complete and then click **Close**.

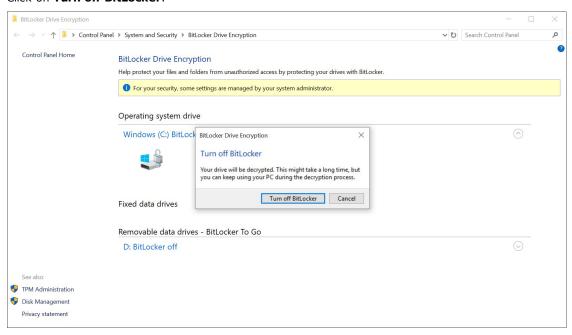


Disabling the BitLocker

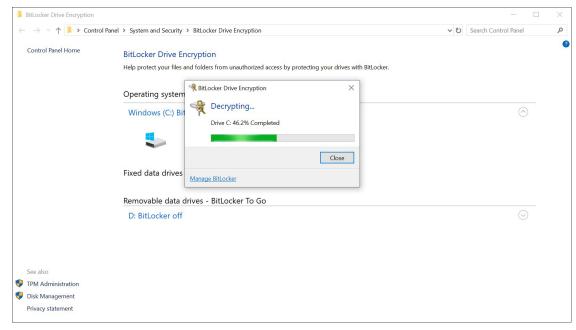
1. In the Windows Devices and drives, right-click on the drive and select Manage BitLocker.

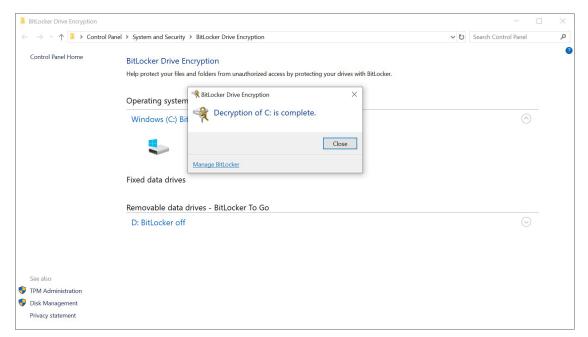


2. Click on Turn off BitLocker.

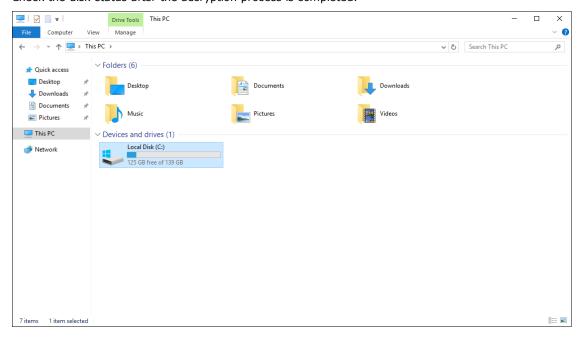


3. Wait for the decryption process to complete and click **Close** to exit the program.





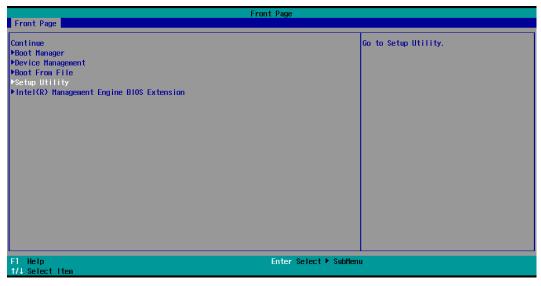
4. Check the disk status after the decryption process is completed.



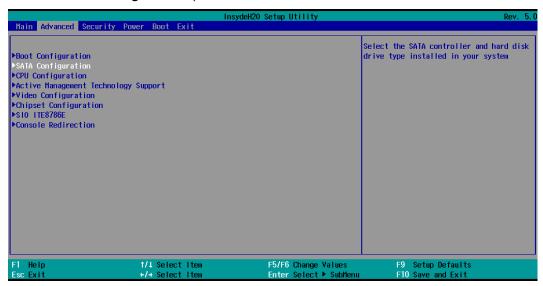
This chapter describes the setup process for RAID.

Changing the RAID Mode

- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select the Setup Utility option.

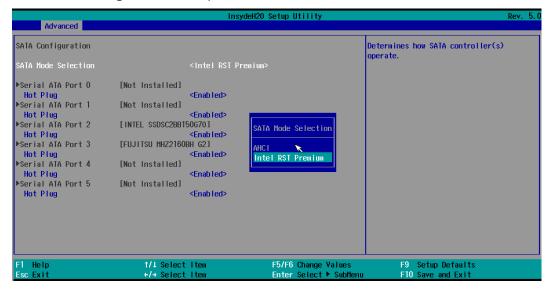


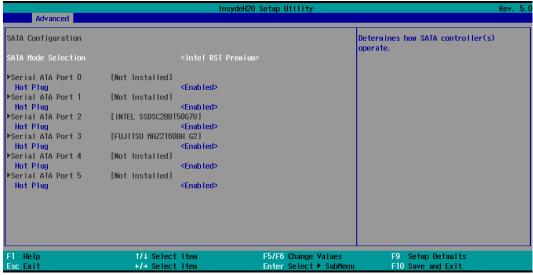
3. Select the **SATA Configuration** option.



4. If your device processor is older than 11th Gen Intel® Core™ Processor (Intel® Tiger-Lake), select the SATA Mode Selection followed by the Intel RST Premium option.

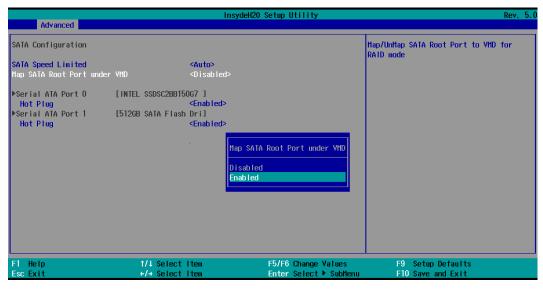
Enable the Hot Plug function on all ports.

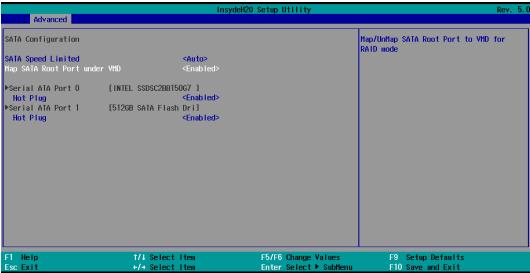




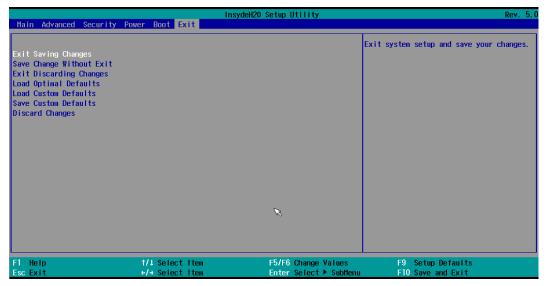
5. If your device CPU is **11th Gen Intel® Core™ Processors (Intel® Tiger-Lake)** or newer processor generation, select the **Map SATA Root Port under VMD** and **Enable** this option.

Enable the Hot Plug function on all ports.

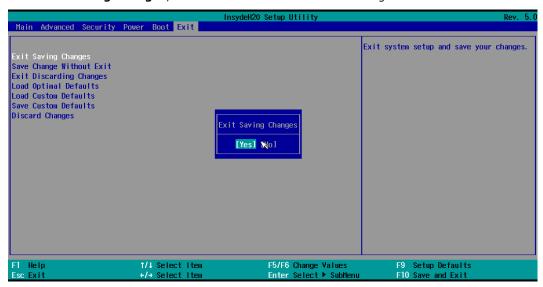




6. Press F10 to save the settings and then press ESC to return to the main page.

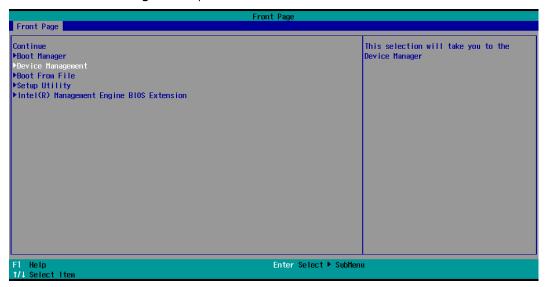


7. Select Exit Saving Changes, and then select Yes to save the settings.



Creating a RAID Disk in BIOS

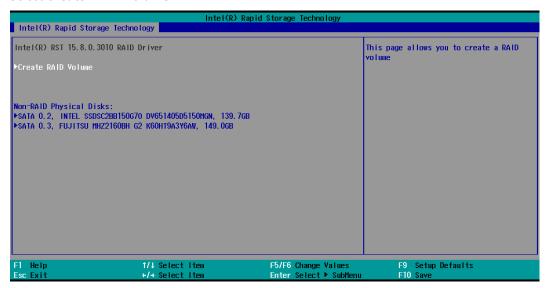
- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select the **Device Management** option.



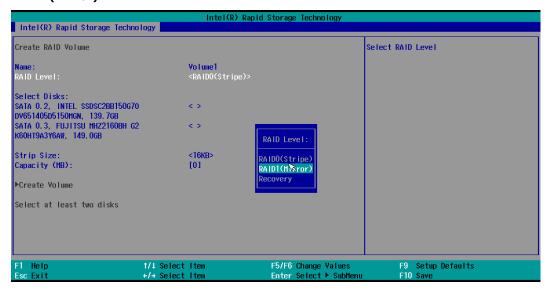
3. Select Intel® Rapid Storage Technology.

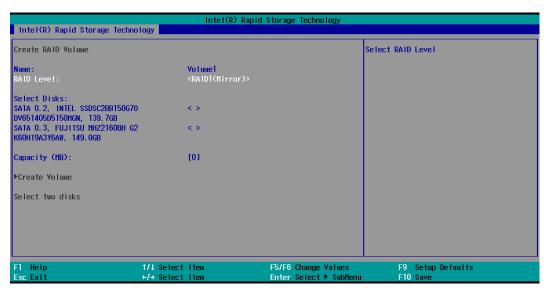


4. Select Create RAID Volume.

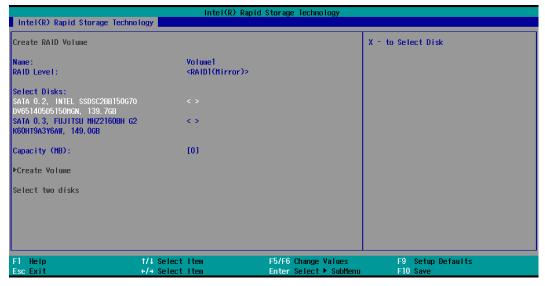


Select the RAID Level option and then press Enter to select the raid level; for example, RAID1(Mirror).

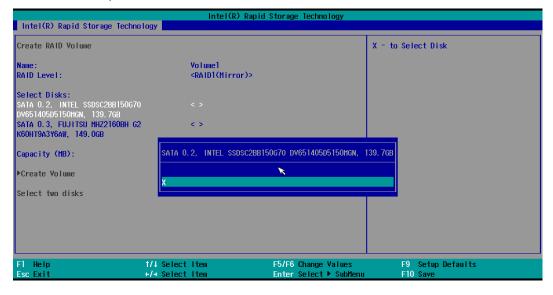




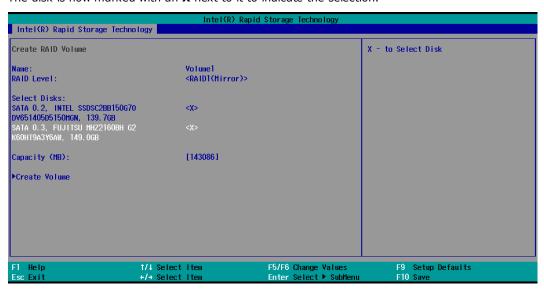
6. Select the target disk.



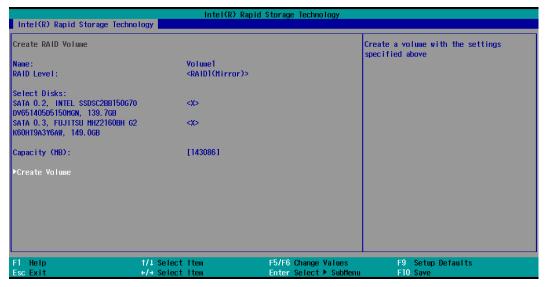
7. Enter **X** and then press **Enter**.



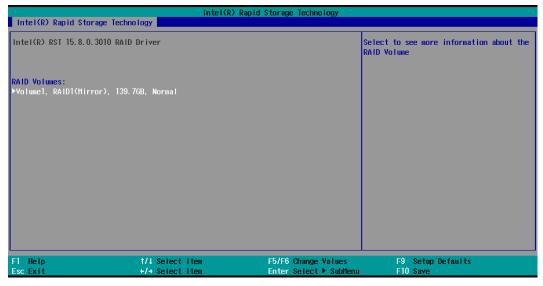
8. The disk is now marked with an **X** next to it to indicate the selection.



9. Select the Create Volume option.



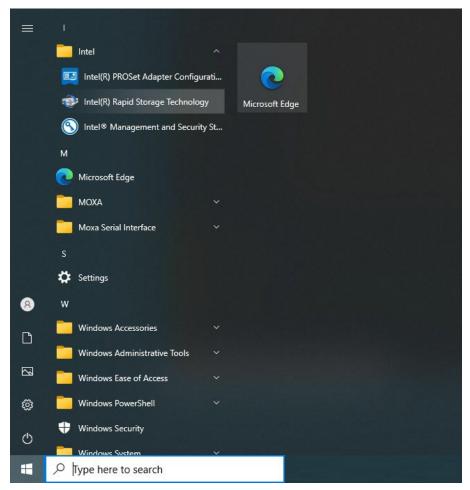
10. A RAID volume is created based on the settings specified.



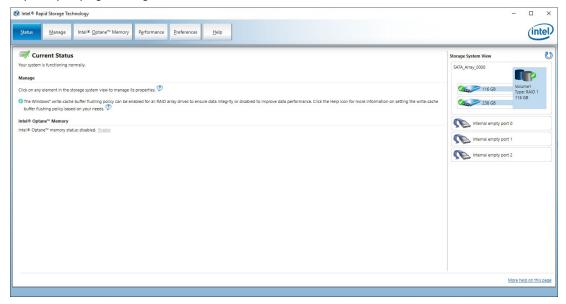
11. Press F10 to save the settings.

Replacing a Disk

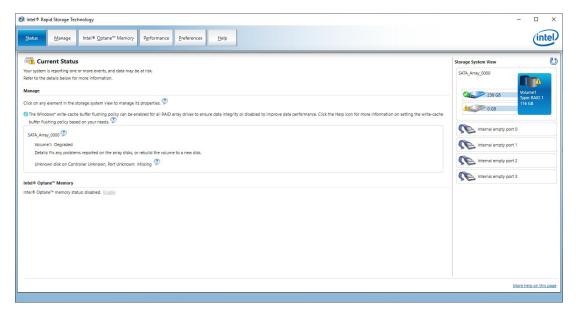
1. Run Intel® Rapid Storage Technology from the Windows Start menu.



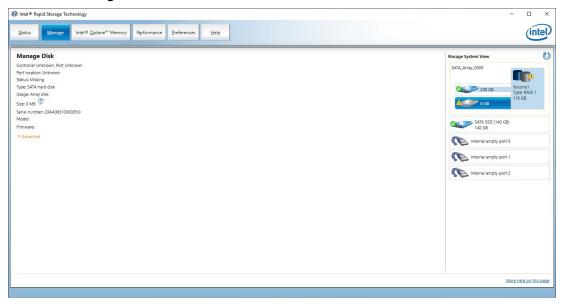
2. Physically unplug the target SSD.



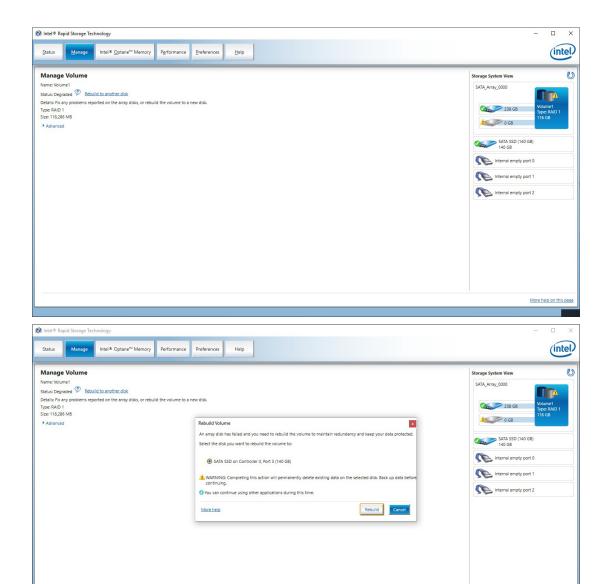
The status of the SSD that is unplugged will change from green (check mark) to yellow (exclamation mark) as shown below:



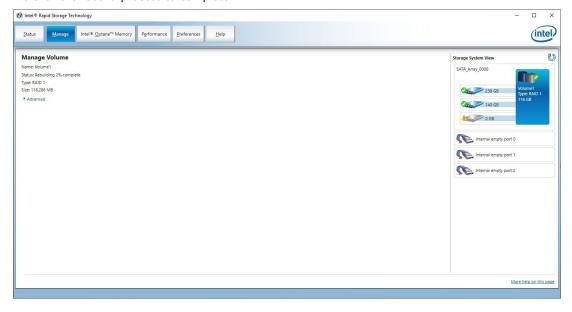
- 3. Install the new SSD.
- 4. Click on the Manage tab.



5. Select the new SSD and click **Rebuild**.

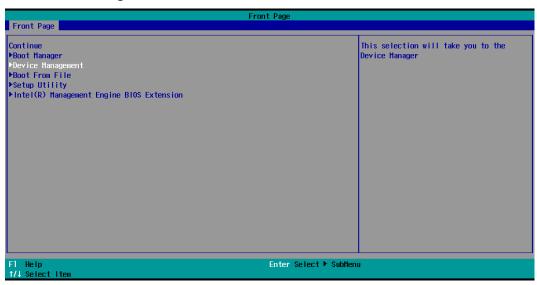


6. Wait for the rebuild process to complete.

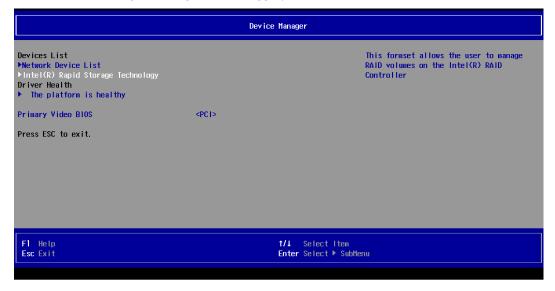


Removing a RAID Volume From the BIOS

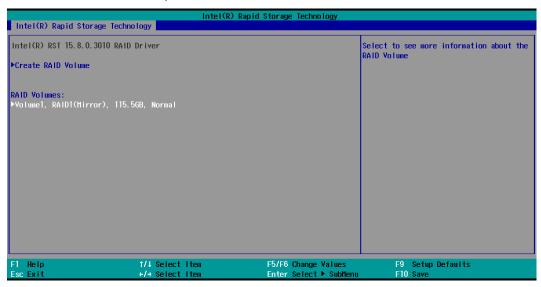
- 1. Power on the computer and press **F2** to enter the BIOS menu.
- 2. Select Device Management.



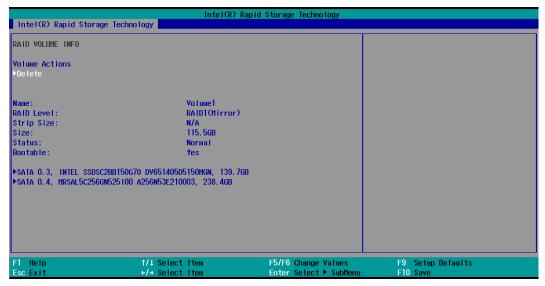
3. Select the Intel® Rapid Storage Technology option.



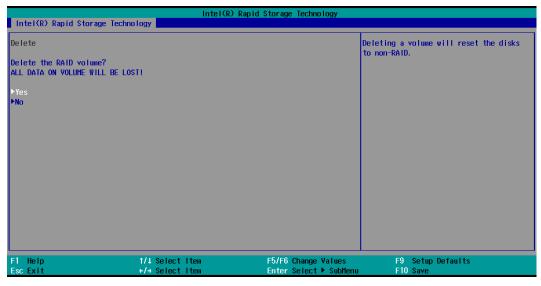
4. Select the RAID volume that you want to remove.



5. Select Delete and then press Enter.



6. Select **Yes** to confirm and then press **Enter**.

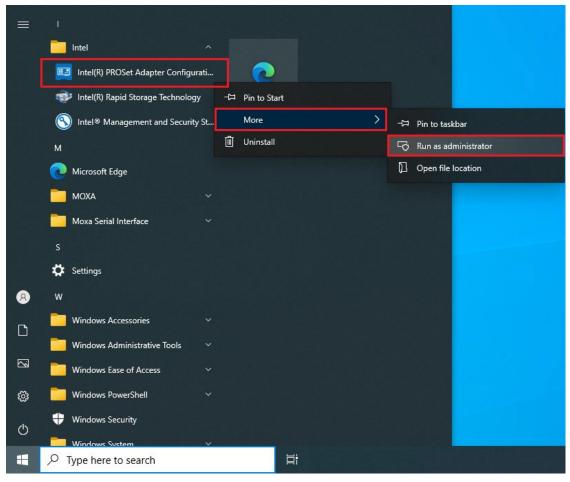


7. Press F10 to save the settings.

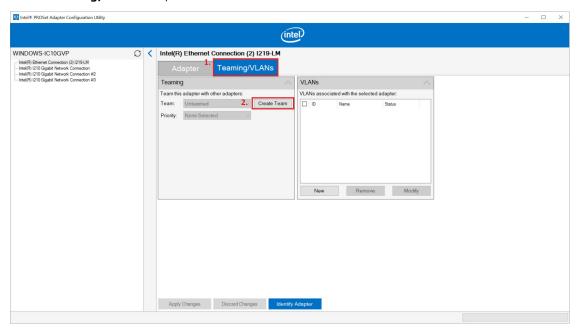
This chapter describes the setup process for the Intel® Teaming function.

Creating an Intel® Net Team

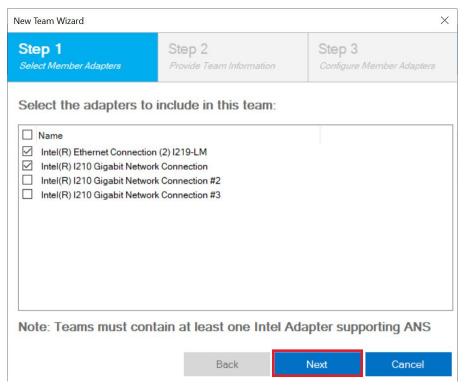
1. Run the Intel® PROSet Adapter Configuration Utility as administrator.



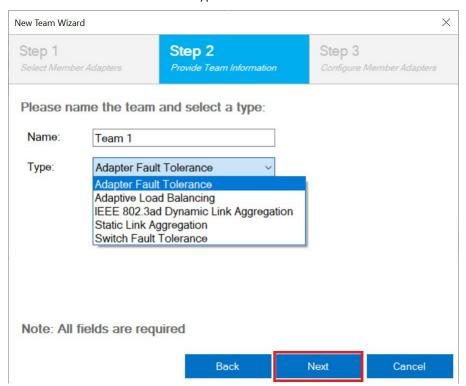
2. In the **Teaming/VLANs** tab, click **Create** Team.



Select the adapter to include in this team and click Next. An Intel ANS team can contain a maximum of eight members.



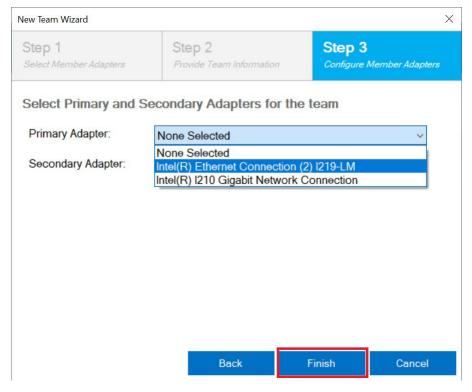
4. Name the team and select a team type. Click **Next** to continue.



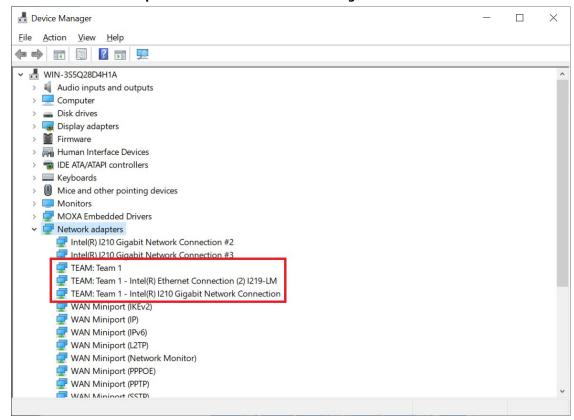
NOTE

You cannot use an Intel AMT enabled adapter in a Dynamic Link Aggregation (DLA) team. You cannot use an Intel AMT enabled adapter in a Static Link Aggregation (SLA) team.

5. Select the primary and secondary adapters for the team and click **Finish** to create an Intel net team.



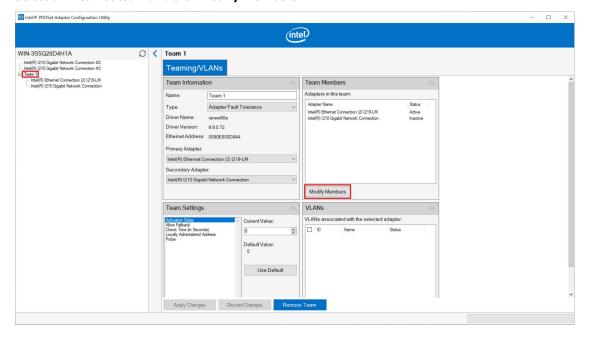
6. Check the Network adapters in the Windows Device Manager.



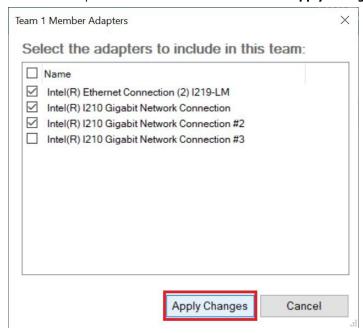
Modifying an Intel® Net Team Member

Adding an Intel® Net Team Member

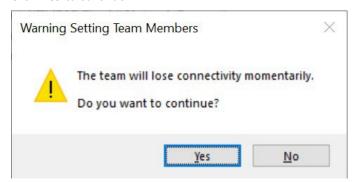
1. Select an Intel net team and click Modify Members.



2. Select the adapters to include in this team and click **Apply Changes**.



3. Click **Yes** to continue.

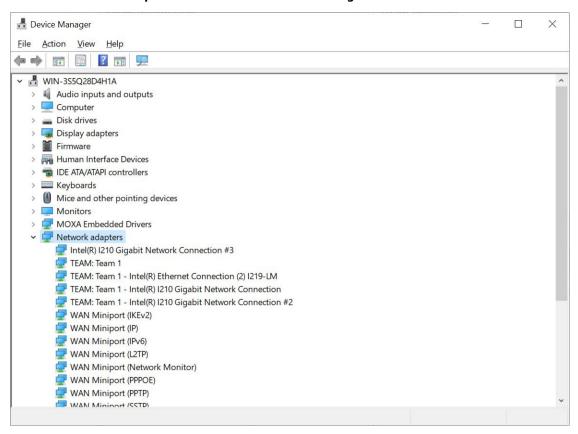




NOTE

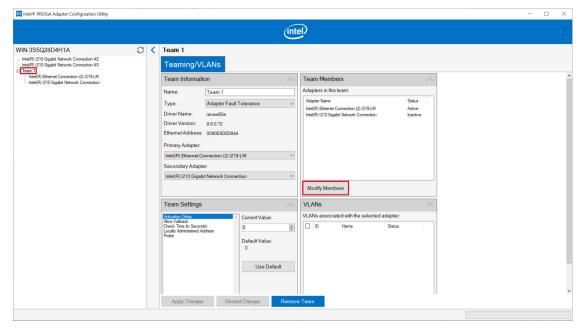
Modifying team members will cause the members to momentarily lose connectivity.

4. Check the Network adapters in the Windows Device Manager.

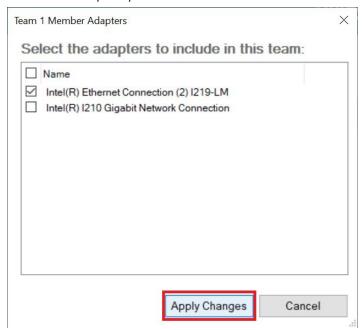


Removing an Intel® Net Team Member

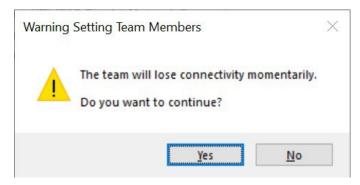
1. Select an Intel net team and click **Modify Members**.



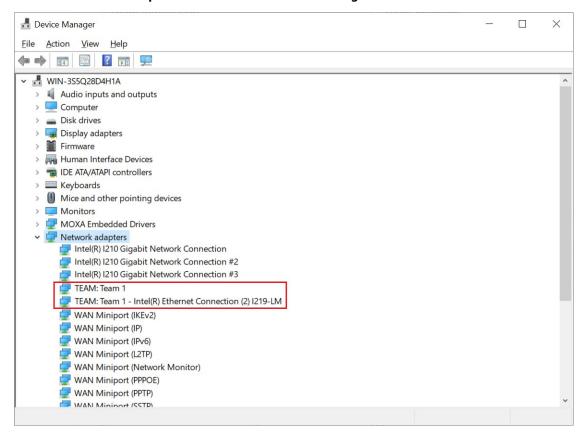
2. Uncheck the adapters you want to remove in this team and click **Apply Changes**.



3. Click **Yes** to continue.

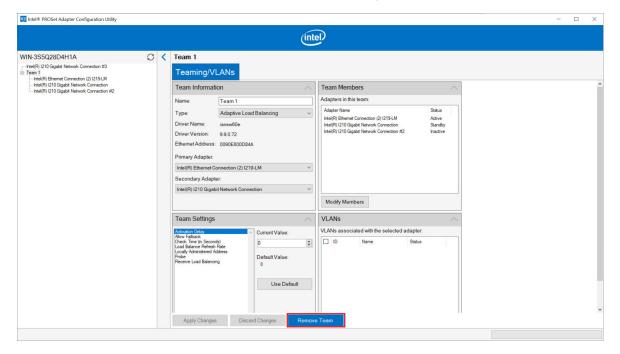


4. Check the Network adapters in the Windows Device Manager.



Removing an Intel® Net Team

Select an Intel net team and click Remove Team to remove the specified Intel ANS team.



6. Unified Write Filter

This chapter describes how to use the Unified the Write Filter (UWF).

To use the UWF, you must first install the feature and enable it; the default is disable.

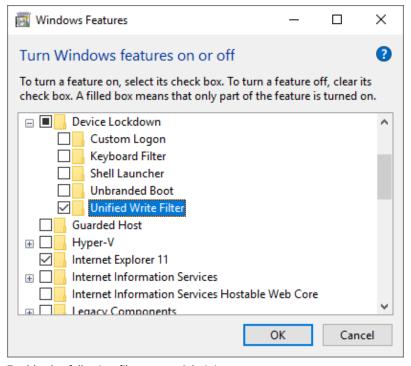
The first time you enable UWF on your device, UWF makes the following changes to your system to improve its performance:

- · Paging files are disabled.
- · System restore is disabled.
- · SuperFetch is disabled.
- · File indexing service is turned off.
- · Fast boot is disabled.
- · Defragmentation service is turned off.
- BCD setting bootstatuspolicy is set to ignoreallfailures.

After UWF is enabled, you can select a drive that you want to protect and start using UWF. UWF can help you manage PCs and devices remotely using WMI.

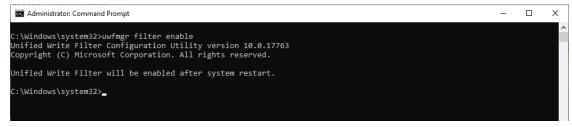
Turning on UWF on a Running PC

- 1. Install UWF.
 - a. In the Windows Start window, type Turn Windows features on or off.
 - b. Open the Windows Features window and expand the Device Lockdown node.
 - c. Select Unified Write Filter and click OK.
 - d. Windows searches for the required files and displays a progress bar. Once the files are found, Windows applies the changes. When the changes are complete, a message to this effect is displayed.
 - e. Click Close.



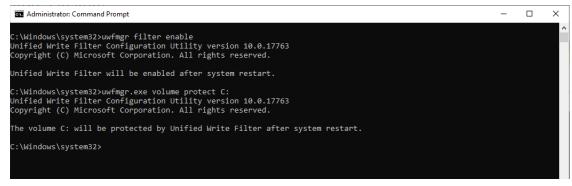
2. Enable the following filter as an Administrator:

cmd uwfmgr filter enable



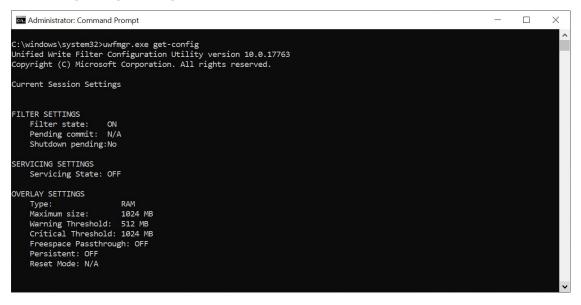
3. Enable write protection for a drive:

cmd uwfmgr.exe volume protect C:



- 4. Restart your computer.
- 5. Confirm that UWF is running:

cmd uwfmgr.exe get-config



Installing UWF Using WMI

If you have already installed Windows on your computer and you do not want to use a provisioning package, you can configure UWF by using Windows Management Instrumentation (WMI) providers. To turn on UWF using WMI, use the **UWF_Filter** function, specifically the **UWF_Filter.Enable** method in one of the following ways:

- Use the WMI providers directly in a PowerShell script
- · Use the WMI providers directly in an application
- Use the command line tool, uwfmgr.exe



NOTE

You must restart your computer after you turn on or turn off UWF for the changes to take effect.

You can also change the settings after you turn on UWF. For example, you can move the page file location to an unprotected volume and re-enable paging files.



IMPORTANT!

If you add UWF to your image by using SMI settings in the unattend.xml file, turning on UWF only sets the bootstatuspolicy BCD setting and turns off the defragmentation service. You must manually turn off the other features and services if you want to increase the performance of UWF.

After the device is restarted, UWF maintains configuration settings for the current session in a registry. UWF automatically excludes these registry entries from its filter. Static configuration changes do not take effect until after a device restart; the changes are saved in registry entries for use in the next session. Dynamic configuration changes occur immediately and persist after a device restart.

7. Moxa IO Controller Utility

This chapter describes how to use the Moxa IO Controller utility.

```
Microsoft Windows [Version 10.0.17763.292]
(c) 2018 Microsoft Corporation. All rights reserved.

C:\Windows\system32>cd /d C:\Program Files\Moxa\Moxa Computer IO Controller

C:\Program Files\Moxa\Moxa Computer IO Controller>_
```

To use the Moxa IO Controller utility, first install the utility and enable the utility to configure the DIO, UART mode, and SIM settings. After the installation process is complete, run the Windows command prompt as an Administrator and change the path to C:\Program Files\Moxa\Moxa Computer IO Controller.

Setting the DIO Status

Type the **mx-dio-ctl --help** command to see the instructions on using this utility and follow them to get or set the DIO status.



IMPORTANT!

The DIN and DOUT indices start at 0. Even though the console output starts at 1, the indices still start at 0.

```
C:\Program Files\Moxa\Moxa IO Controller>mx-dio-ctl.exe --help
mx-dio-ctl 1.2.2201.10100
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get value from DIN port 1:
    mx-dio-ctl -i 1
    Get value from DOUT port 1:
    mx-dio-ctl -o 1
Set DOUT port 2 value to HIGH:
    mx-dio-ctl -m 1 -o 2

-i (Group: Index) -i <#DIN index> (Start from 0)

-o (Group: Index) -o <#DOUT index> (Start from 0)

-m -m <status>
    0 --> LOW
    1 --> HIGH

--help Display this help screen.

--version Display version information.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>_
```

Example:

Setting the UART Mode

Type the **mx-uart-ctl** --help command to see instructions on using this utility and follow the onscreen instructions to get or set the UART mode.



IMPORTANT!

The UART index starts from **0**. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa IO Controller>mx-dio-ctl -i 0
DIN port 0 status: 1

C:\Program Files\Moxa\Moxa IO Controller>mx-uart-ctl.exe --help
mx-uart-ctl 1.4.2201.10000
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get uart mode from port 2:
mx-uart-ctl -p 2
Set port 1 to mode RS-422:
mx-uart-ctl -m 2 -p 1

-p Required. -p <#port index> (Start from 0)

-m -m <#uart mode>
0 --> set to RS232 mode
1 --> set to RS482-2W mode
2 --> set to RS422/RS485-4W mode
--help Display this help screen.

--version Display version information.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>_

C:\Program Files\Moxa\Moxa\Moxa IO Controller>_
```

```
Administrator: Command Prompt

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-uart-ctl -p 0
Current uart mode is RS232 interface.

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-uart-ctl -p 0 -m 1
Set OK.

Current uart mode is RS485-2W interface.

C:\Program Files\Moxa\Moxa Computer IO Controller>_
```

Setting the Relay Status

Type the **mx-relay-ctl --help** command to see instructions on using this utility and follow the onscreen instructions to get or set the relay status.



IMPORTANT!

The relay index starts from $\mathbf{0}$. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa IO Controller>mx-relay-ctl.exe --help
mx-relay-ctl 1.0.1905.0
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get value from relay index 1:
mx-relay-ctl -i 1
Turn on relay index 2:
mx-relay-ctl -i 2 -m 1

-i Required. -i <#Relay index> (Start from 0)

-m -m <status>
0 --> turn off
1 --> turn on

--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa IO Controller>__
```

```
Administrator. Command Prompt

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-relay-ctl -i 0
Relay index 0 data: 1

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-relay-ctl -i 0 -m 0
Relay index 0 data: 0

C:\Program Files\Moxa\Moxa Computer IO Controller>
```

Setting the LED Status

Type the **mx-led-ctl --help** command to see instructions on using this utility and follow the onscreen instructions to get or set the LED status.



IMPORTANT!

The relay index starts from $\mathbf{0}$. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa IO Controller>mx-led-ctl.exe --help
mx-led-ctl 1.0.1905.0
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get value from LED index 1:
mx-led-ctl -i 1
Turn on LED index 2:
mx-led-ctl -i 2 -m 1
Set LED index 3 to blink mode:
mx-led-ctl -i 3 -m 2

-i Required. -i <#LED index> (Start from 0)

-m -m <status>
0 --> led off
1 --> led on
2 --> led blink

--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>_
```

```
C:\Program Files\Moxa\Moxa Computer IO Controller>mx-led-ctl -i 0
LED index 0 data: 0

C:\Program Files\Moxa\Moxa Computer IO Controller>mx-led-ctl -i 0 -m 1
LED index 0 data: 1

C:\Program Files\Moxa\Moxa Computer IO Controller>_
```

Setting the SIM Status

Type the **mx-sim-ctl --help** command to see instructions on using this utility and follow the onscreen instructions to get or set the status of the SIM card slot.

```
Administrator Command Prompt

C:\Program Files\Moxa\Moxa IO Controller>mx-sim-ctl.exe -s 1

Module socket 1 SIM slot: 1

C:\Program Files\Moxa\Moxa IO Controller>mx-sim-ctl.exe -s 1 -i 2

Waiting for module power off...

Waiting for module power on...

Module socket 1 SIM slot: 2

C:\Program Files\Moxa\Moxa IO Controller>mx-sim-ctl.exe -s 1

Module socket 1 SIM slot: 2

C:\Program Files\Moxa\Moxa IO Controller>mx-sim-ctl.exe -s 1

C:\Program Files\Moxa\Moxa IO Controller>mx-sim-ctl.exe -s 1
```

Setting PCIE Slot Power Status

Type the **mx-pcie-ctl --help** command to see instructions on using this utility and follow the onscreen instructions to get or set the status of the PCIE slot power.



IMPORTANT!

The PCIE Slot index starts from $\mathbf{0}$. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa\Moxa IO Controller>mx-pcie-ctl.exe --help
mx-pcie-ctl 1.2.1907.10000
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Get pcie power status from pcie slot 1:
    mx-pcie-ctl -i 1
    set pcie slot 1 power on:
    mx-pcie-ctl -i 1 -m 1
    Set pcie slot 1 power on with delay Time 200ms:
    mx-pcie-ctl -i 1 -m 1 -t 200

-i    Required. -i <#PCIE Slot index> (Start from 0)

-m    -m -m -m -m -pCIE power off
1 --> PCIE power on

-t    -t <#PCIE Reset Delay time(ms)>
--help    Display this help screen.
--version    Display version information.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>_
```

```
Administrator. Command Prompt

C:\Program Files\Moxa\Moxa IO Controller>mx-pcie-ctl.exe -i 0

PCIE slot 0 power status: 1

C:\Program Files\Moxa\Moxa IO Controller>mx-pcie-ctl.exe -i 0 -m 0

PCIE slot 0 power status: 0

C:\Program Files\Moxa\Moxa IO Controller>
```

Setting PCIE Reset Pin Status

Type the **mx-pciereset-ctl** --help command to see instructions on using this utility and follow the onscreen instructions to get or set the PCIE reset pin status and delay time.



IMPORTANT!

The PCIE reset pin index starts from $\mathbf{0}$. Even though the console output starts at 1, the index still starts at 0.

```
C:\Program Files\Moxa\Moxa IO Controller>mx-pciereset-ctl.exe --help
mx-reset-ctl 2.0.2203.10000
Copyright (C) 2019 Moxa Inc. All rights reserved.
USAGE:
Reset PCIE slot 1:
    mx-pciereset-ctl -i 1
Reset PCIE slot 1 DelayTime 200ms:
    mx-pciereset-ctl -i 1 -t 200

-i Required. -i <#PCIE Reset Slot index> (Start from 0)

-t -t <#PCIE Reset Delay time(ms)>
--help Display this help screen.
--version Display version information.

C:\Program Files\Moxa\Moxa IO Controller>_
```

```
Administrator Command Prompt

C:\Program Files\Moxa\Moxa IO Controller>mx-pciereset-ctl.exe -i 0
PCIE slot 0 reset status: 1

C:\Program Files\Moxa\Moxa IO Controller>mx-pciereset-ctl.exe -i 0 -t 200
PCIE slot 0 reset status: 1

C:\Program Files\Moxa\Moxa IO Controller>
```

Setting M.2 B Key Socket 5G Module Power Status

Type the **mx-5Gpower-ctl --help** command to see instructions on using this utility and follow the onscreen instructions to get or set the status of the M.2 B Key socket power.

```
Administrator.Command Prompt

C:\Program Files\Moxa\Moxa IO Controller>mx-5Gpower-ctl.exe -s 1
5G module status: ON

C:\Program Files\Moxa\Moxa IO Controller>mx-5Gpower-ctl.exe -p 0 -s 1
Waiting for module power off...
SetMZBMainPower off success!
Set 5G module power off.

C:\Program Files\Moxa\Moxa IO Controller>mx-5Gpower-ctl.exe -p 1 -s 1
SetMZBMainPower on success!
Waiting for module power on...
Set 5G module power on.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>mx-5Gpower-ctl.exe -r -s 1
sleep:600
5G module reset.

C:\Program Files\Moxa\Moxa\Moxa IO Controller>

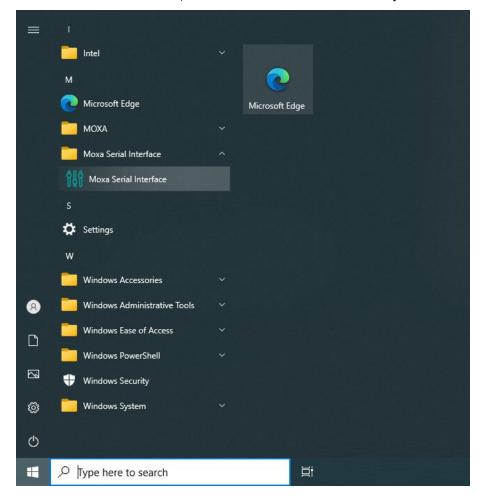
C:\Program Files\Moxa\Moxa\Moxa IO Controller>
```

8. Moxa Serial Interface Utility

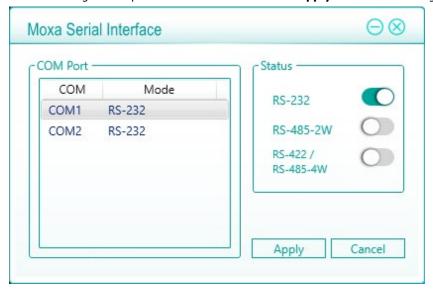
In this chapter, we describe how to use the Moxa Serial Interface utility to set the UART mode in your computer's serial interface.

Setting the Serial Port Mode

- 1. Install the Moxa Serial Interface utility.
- 2. From the Windows Start menu, run the Moxa Serial Interface utility.



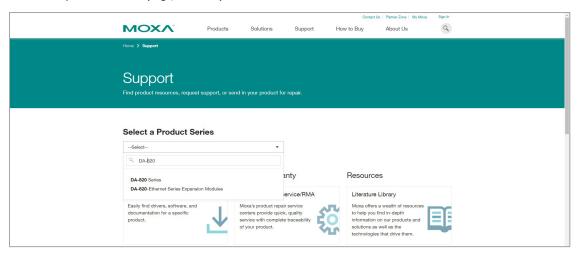
3. Select the target COM port and UART mode and click **Apply** to save the settings.



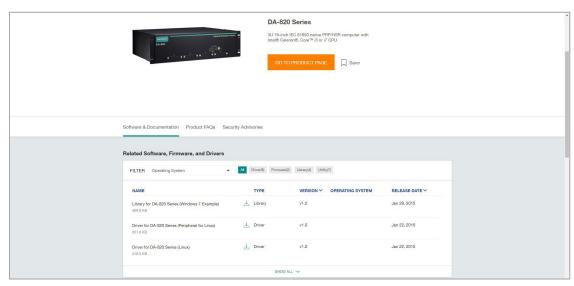
This chapter describes how to use the IO Control API.

Downloading the API

- 1. Access the Moxa support page: https://www.moxa.com/en/support
- 2. Select the product series (e.g., DA-820).



3. Download the related files.



Supported Series

mxdgio

- DA-681C Series
- DA-682C Series
- DA-820C Series
- V2403C Series
- V2406C Series
- MC-3201 Series

mxsp

- DA-681C Series
- DA-682C Series
- DA-820C Series
- V2403C Series
- V2406C Series
- MC-1200 Series
- MC-3201 Series

mxrelay

- DA-681C Series
- DA-682C Series
- DA-820C Series

mxled

- DA-681C Series
- DA-682C Series
- DA-820C Series
- V2403C Series

mxsim

- V2403C Series
- V2406C Series
- MC-1200 Series
- MC-3201 Series

mxpcie

- V2403C Series
- V2406C Series
- MC-1200 Series
- MC-3201 Series

mxpciereset

MC-3201 Series

mx5Gpower

MC-3201 Series

mxwdg

- DA-681C Series
- DA-682C Series
- DA-820C Series
- V2403C Series
- V2406C Series
- MC-1200 Series
- MC-3201 Series

mxdgio

The **mxdgio** library operates on the digital I/Os and consists of the following:

- GetDinStatus
- GetDoutStatus
- SetDoutStatus

GetDinStatus

Syntax

int GetDinStatus(int port);

Description

Gets the status of a digital input port.

Parameters

port: The index of the digital input port; starts at 0.

Return Value

The status of the digital input port; 0 for low and 1 for high.

Error codes

The following error codes can be retrieved by the **DIO_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization failed. Cannot open the json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items	
Header	mxdgio.h	
Library	mxdgio.lib	
DLL	mxdgio.dll	
Profile	MxdgioProfile [ModelName].json	

GetDoutStatus

Syntax

int GetDoutStatus(int port);

Description

Gets the status of a digital output port.

Parameters

port: The index of the digital output port; starts at 0.

Return Value

The status of the digital output port; 0 for low and 1 for high.

Error codes

The following error codes can be retrieved by the **DIO_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Requirements

Name	Items
Header	mxdgio.h
Library	mxdgio.lib
DLL	mxdgio.dll
Profile	MxdgioProfile [ModelName].json

SetDoutStatus

Syntax

int SetDoutStatus(int port, int status);

Description

Sets the status of a digital output port.

Parameters

port: The index of the digital output port; starts at 0.

status: The status of the digital output port; 0 for low and 1 for high.

<u>Return Value</u>

Returns the value 0 if the digital output status is successfully set.

Error codes

The following error codes can be retrieved by the **DIO_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxdgio library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxdgio.h
Library	mxdgio.lib
DLL	mxdgio.dll
Profile	MxdgioProfile [ModelName].json

mxsp

The \boldsymbol{mxsp} library operates on the serial port and consists of the following:

- GetUartMode
- SetUartMode

GetUartMode

Syntax

int GetUartMode(int port);

Description

Gets the status of the UART port.

Parameters

port: The index of the UART port; starts at 0.

Return Value

The mode of a UART interface; 0 for RS-232, 1 for RS-485-2W, and 2 for RS-422/RS-485-4W.

Error codes

The following error codes can be retrieved by the $\textbf{UART_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsp library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items
Header	mxsp.h
Library	mxsp.lib
DLL	mxsp.dll
Profile	MxspProfile [ModelName].json

SetUartMode

Syntax

int SetUartMode(int port, int mode);

Description

Sets the status of the UART port.

Parameters

port: The index of the UART port; starts at 0.

mode: The mode of a UART interface; 0 for RS-232, 1 for RS-485-2w, and 2 for RS-422/RS-485-4W.

Return Value

Returns 0 if the UART mode is successfully set.

Error codes

The following error codes can be retrieved by the **UART_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsp library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxsp.h
Library	mxsp.lib
DLL	mxsp.dll
Profile	MxspProfile [ModelName].json

mxrelay

The ${\it mxrelay}$ library operates on the relay output and consists of the following:

- GetRelayData
- SetRelayData

GetRelayData

Syntax

int GetRelayData(int port);

Description

Gets the status of the relay output port.

Parameters

port: The index of the relay output port; starts at 0.

Return Value

The status of a relay output port; 0 for OFF, 1 for ON.

Error codes

The following error codes can be retrieved by the $\textbf{RELAY_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxrelay library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items
Header	mxrelay.h
Library	mxrelay.lib
DLL	mxrelay.dll
Profile	MxrelayProfile [ModelName].json

SetRelayData

Syntax

int SetRelayData(int port, int status);

Description

Sets the status of the relay output port.

Parameters

port: The index of the relay output port; starts at 0. status: The status of a relay output; 0 for OFF, 1 for ON

Return Value

Returns 0 if the status of the relay output is successfully set.

Error codes

The following error codes can be retrieved by the **RELAY_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxrelay library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header mxrelay.h	
Library mxrelay.lib	
DLL mxrelay.dll	
Profile	MxrelayProfile [<i>ModelName</i>].json

mxled

The \boldsymbol{mxled} library operates on the relay output and consists of the following:

- GetLedData
- SetLedData

GetLedData

Syntax

int GetLedData(int port);

Description

Gets the status of the LED port.

Parameters

port: The index of the LED port; starts at 0.

Return Value

The status of a LED port; 0 for OFF, 1 for ON.

Error codes

The following error codes can be retrieved by the $\textbf{LED_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxled library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items
Header	mxled.h
Library	mxled.lib
DLL	mxled.dll
Profile	MxledProfile [ModelName].json

SetLedData

Syntax

int SetLedData(int port, int status);

Description

Sets the status of the LED port.

Parameters

 $\ensuremath{\textit{port:}}$ The index of the LED port; starts at 0.

status: The status of the LED; 0 for OFF, 1 for ON, and 2 for blinking.

Return Value

Returns 0 if the LED status is set successfully.

Error codes

The following error codes can be retrieved by the ${\bf LED_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxled library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxled.h
Library	mxled.lib
DLL	mxled.dll
Profile	MxledProfile [ModelName].json

mxsim

The \boldsymbol{mxsim} library operates on the relay output and consists of the following:

- GetSIMSlot
- SetSIMSlot

GetSIMSlot

Syntax

int GetSIMSlot(int port);

Description

Gets the SIM card slot index number.

Parameters

port: The index of the SIM card slot; starts at 0.

Return Value

The SIM card slot number; 1 for SIM 1 slot, 2 for SIM 2 slot.

Error codes

The following error codes can be retrieved by the ${\bf SIM_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsim library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items
Header	mxsim.h
Library mxsim.lib	
DLL	mxsim.dll
Profile	MxsimProfile [ModelName].json

SetSIMSlot

Syntax

int SetSIMSlot(int port, int slot);

Description

Sets the SIM card slot.

Parameters

port: The index of the SIM card slot; starts at 0.

slot: The SIM card slot of a SIM number; 0 is SIM 1 slot, 1 is SIM 2 slot.

Return Value

Returns 0 if the SIM card slot of the SIM number is successfully set.

Error codes

The following error codes can be retrieved by the ${\bf SIM_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxsim library initialization failed. Cannot open the json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items	
Header	mxsim.h	
Library	mxsim.lib	
DLL	mxsimdll	
Profile	MxsimProfile [<i>ModelName</i>].json	

mxpcie

The \boldsymbol{mxpcie} library operates on the relay output and consists of the following:

- GetPCIESIotStatus
- SetPCIESIotStatus
- SetPCIESIotStatus

GetPCIESIotStatus

Syntax

int GetPCIESlotStatus(int port);

Description

Gets the PCIE slot power status.

Parameters

port: The index of the PCIE slot; starts at 0.

Return Value

The status of a PCIE slot power; 0 for OFF, 1 for ON.

Error codes

The following error codes can be retrieved by the ${f PCIE_STATUS}$ function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxpcie library initialization failed. Cannot open json profile.
PORT OUTOF INDEX	-2	Target port index is out of range.

Name	Items
Header	mxpcie.h
Library	mxpcie.lib
DLL	mxpcie.dll
Profile	MxpcieProfile [ModelName].json

SetPCIESIotStatus

Syntax

int SetPCIESlotStatus(int port, int status);

Description

Sets the PCIE slot power status.

Parameters

port: The index of the PCIE slot; starts at 0.

status: The status of the PCIE slot power; 0 for OFF, 1 for ON.

Return Value

Returns 0 if the PCIE slot power is successfully set.

Error codes

The following error codes can be retrieved by the **PCIE_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxpcie library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET STATUS ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxpcie.h
Library	mxpcie.lib
DLL	mxpcie.dll
Profile	MxpcieProfile [ModelName].json

SetPCIESIotStatusWithReset

Syntax

int SetPCIESlotStatusWithReset(int port, int status, int time);

Description

Sets the PCIE slot power status and PCIE slot reset pin turn ON and OFF.

<u>Parameters</u>

port: The index of the PCIE slot; starts at 0.

status: The status of the PCIE slot power and PICE reset pin; 0 for OFF, 1 for ON.

time: The delay time between PCIE slot reset pin turn ON and OFF.

Return Value

Returns 0 if the PCIE slot power and PCIE reset pin are successfully set.

Error codes

The following error codes can be retrieved by the **PCIE_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxpcie library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxpcie.h
Library	mxpcie.lib
DLL	mxpcie.dll
Profile	MxpcieProfile [<i>ModelName</i>].json

mxpciereset

The ${\bf mxpciereset}$ library operates on the relay output and consists of the following:

- GetRESETSIotStatus
- SetRESETSlotStatus

GetRESETSlotStatus

Syntax

Description

Gets the PCIE slot reset pin status.

Parameters

port: The index of the PCIE slot; starts at 0.

Return Value

The status of a PCIE slot reset pin; 0 for OFF, 1 for ON.

Error codes

The following error codes can be retrieved by the **RESET_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxpciereset library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.

Name	Items
Header	mxpciereset.h
Library	mxpciereset.lib
DLL	mxpciereset.dll
Profile	MxpcieresetProfile [ModelName].json

SetRESETSIotStatus

Syntax

int SetRESETSlotStatus(int port, int time);

Description

Sets the PCIE slot reset pin ON/OFF cycle and delay time.

Parameters

port: The index of the PCIE slot; starts at 0.

time: The delay time between PCIE slot reset pin turn ON and OFF.

Return Value

Returns 0 if the PCIE slot reset pin is successfully set.

Error codes

The following error codes can be retrieved by the **RESET_STATUS** function.

Name	Value	Meaning
LIB_INITIALIZE_FAIL	-1	The mxpciereset library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-2	Target port index is out of range.
SET_STATUS_ERR	-3	Status setting failed or is defined with a bad format.

Name	Items
Header	mxpciereset.h
Library	mxpciereset.lib
DLL	mxpciereset.dll
Profile	MxpcieresetProfile [ModelName].json

mx5Gpower

The ${f mx5Gpower}$ library operates on the relay output and consists of the following:

- GetPowerStatus
- SetPowerStatus
- ResetModule

GetPowerStatus

Syntax

int GetPowerStatus(int port);

Description

Gets the 5G module power status.

Parameters

port: The index of the M.2 B key slot; starts at 0.

Return Value

The status of a 5G module power; 0 for OFF, 1 for ON.

Error codes

The following error codes can be retrieved by the ${\bf RETURN_STATUS}$ function.

Name	Value	Meaning
ACTION_SUCCESS	0	Action success.
ACTION_ERROR	-1	Action error.
LIB_INITIALIZE_FAIL	-2	The mx5Gpower library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-3	Target port index is out of range.
SET_STATUS_ERR	-4	Status setting failed or is defined with a bad format.
INVALID_MODULE	-5	Invalid module.
ACTION_TIMEOUT	-6	Action timeout.

Name	Items
Header	mx5Gpower.h
Library	mx5Gpower.lib
DLL	mx5Gpower.dll
Profile	Mx5GpowerProfile [<i>ModelName</i>].json

SetPowerStatus

Syntax

int SetPowerStatus(int port, int status);

Description

Sets the 5G module power status.

Parameters

port: The index of the M.2 B key; starts at 0.

status: The status of a 5G module power; 0 for OFF, 1 for ON.

Return Value

Returns 0 if the 5G module power status is successfully set.

Error codes

The following error codes can be retrieved by the **RETURN_STATUS** function.

Name	Value	Meaning
ACTION_SUCCESS	0	Action success.
ACTION_ERROR	-1	Action error.
LIB_INITIALIZE_FAIL	-2	The mx5Gpower library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-3	Target port index is out of range.
SET_STATUS_ERR	-4	Status setting failed or is defined with a bad format.
INVALID_MODULE	-5	Invalid module.
ACTION_TIMEOUT	-6	Action timeout.

Name	Items
Header	mx5Gpower.h
Library	mx5Gpower.lib
DLL	mx5Gpower.dll
Profile	Mx5GpowerProfile [<i>ModelName</i>].json

ResetModule

Syntax

int ResetModule(int port);

Description

Resets the 5G module power status. Run the 5G module power cycle.

Parameters

port: The index of the M.2 B key; starts at 0.

Return Value

Returns 0 if the 5G module power status is successfully set.

Error codes

Name	Value	Meaning
ACTION_SUCCESS	0	Action success.
ACTION_ERROR	-1	Action error.
LIB_INITIALIZE_FAIL	-2	The mx5Gpower library initialization failed. Cannot open json profile.
PORT_OUTOF_INDEX	-3	Target port index is out of range.
SET_STATUS_ERR	-4	Status setting failed or is defined with a bad format.
INVALID_MODULE	-5	Invalid module.
ACTION_TIMEOUT	-6	Action timeout.

Name	Items
Header	mx5Gpower.h
Library	mx5Gpower.lib
DLL	mx5Gpower.dll
Profile	Mx5GpowerProfile [ModelName].json

mxwdg

The ${\it mxwdg}$ library operates on the relay output and consists of the following:

- mxwdg_open
- mxwdg_refresh
- mxwdg_close

mxwdg_open

Syntax

PVOID mxwdg open (unsigned long time);

Description

Initializes the watchdog timer.

Parameters

time: The interval at which the watchdog timer is refreshed; the unit is seconds.

Return Value

Returns the pointer to the watchdog handle; returns -1 on failure to initialize the watchdog timer.

Requirements

Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

mxwdg_refresh

Syntax 5 4 1

int mxwdg_refresh(PVOID fd);

Description

Refreshes the watchdog timer.

Parameters

fd: The handle of the watchdog timer.

Return Value

Returns 0 on success; otherwise, the function has failed.

Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

mxwdg_close

Syntax

void mxwdg_close(PVOID fd);

Description

Disables the watchdog timer.

Parameters

fd: The handle of the watchdog timer.

Return Value

This function does not return a value.

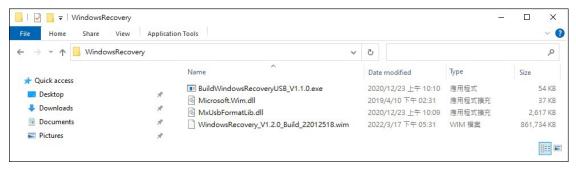
Name	Items
Header	mxwdg.h
Library	mxwdg.lib
DLL	mxwdg.dll

10. Windows Recovery

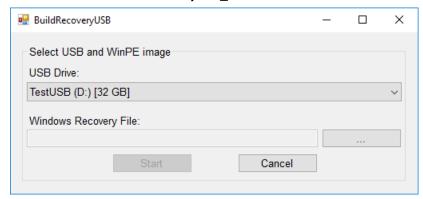
This chapter describes the setup process of the Windows Recovery function.

Preparing the USB device

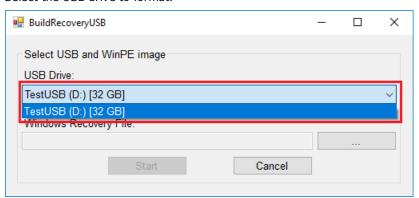
1. Contact a Moxa technical staff and get the required file.



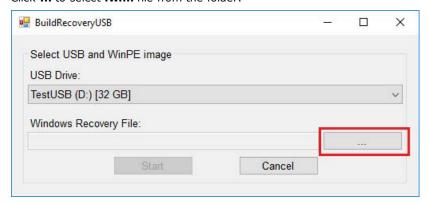
2. Run the BuildWindowsRecoveryUSB_V1.1.0.exe.

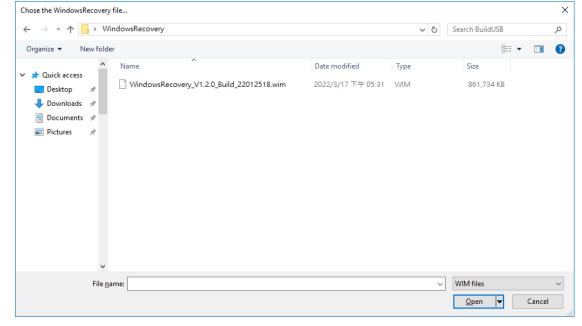


3. Select the USB drive to format.

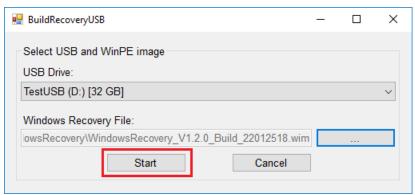


4. Click ... to select .wim file from the folder.



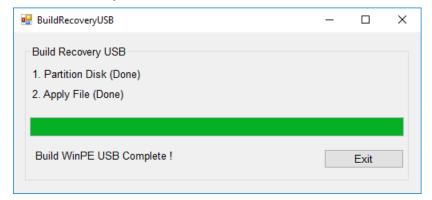


5. Click **Start** and make sure the selected USB can be formatted. Click **Yes** to start creating the recovery USB.

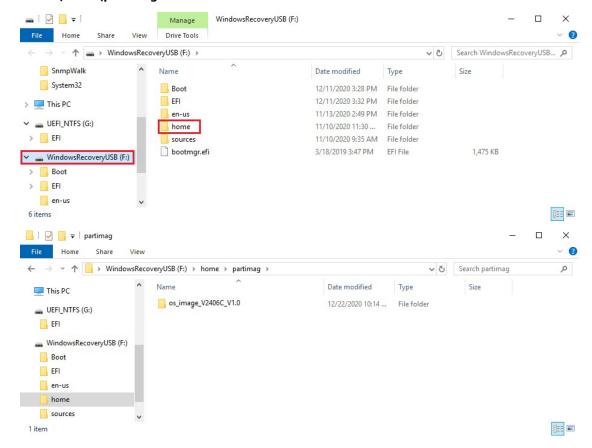


6. Wait for the process finished, the program will format the USB device and create a UEFI bootable volume and a WinPE volume.

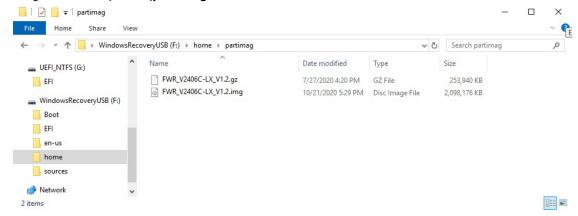
You may see some additional windows about folder information; do not close these. You can close the windows after the process finishes.



7. To create a recovery USB disk with the Windows 10 image, copy the **os_image_ModelName** directory to the **\home\partimag** folder in the USB drive.

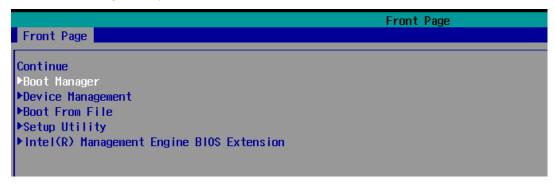


8. To create a recovery USB disk with a Linux image, copy the **ModelName.gz** or **ModelName.img** image file to the **\home\partimag** folder in the USB drive.



Booting From the USB Disk

- 1. Turn on the computer and press **F2** when you hear the beep sound to enter the BIOS setup menu.
- 2. Select Boot Manager and press Enter to continue.



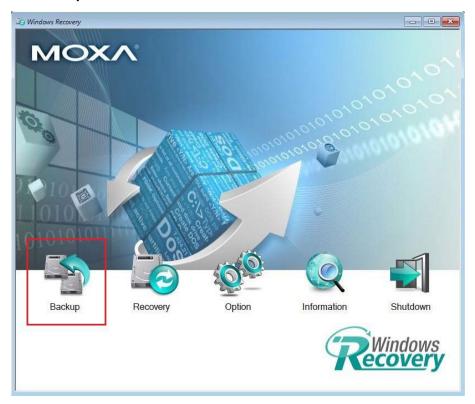
3. Select the EFI USB Device on the computer and press Enter to continue to boot from the USB device.



System Image Backup

To back up the image from the USB disk, run **Windows Preinstallation Environment(WinPE)** and the **Windows Recovery utility** will display. Follow these steps.

1. Click Backup.



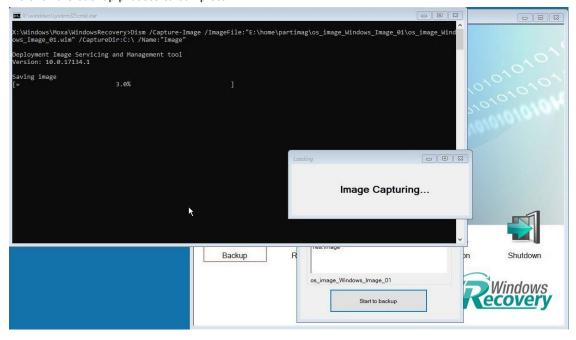
2. Select the **Source disk** to backup and **Destination USB** to store the OS image, also give an image name and description. Click **Start to backup**.



3. Click **Yes** to continue.



4. Wait for the backup process to complete.



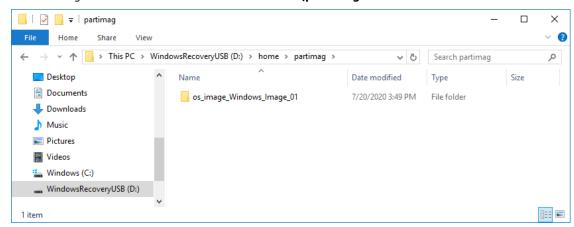
5. When the process is completed, click **OK**.



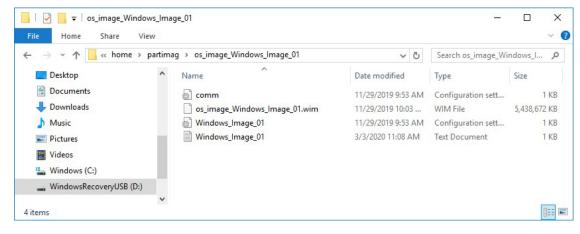
6. Click \mathbf{OK} , the computer will shut down.



7. The OS image will be saved to the USB disk at **home\partimag**.



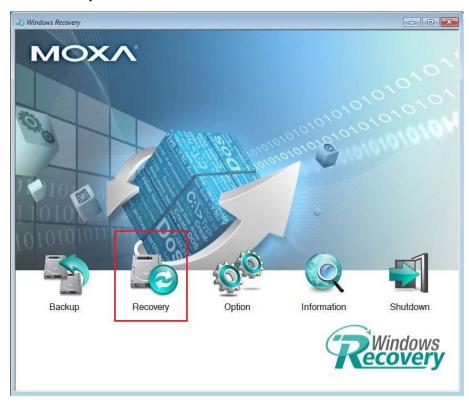
8. In the **os_image** folder you can view the backup information and the image files.



Restoring the System From a Backup

To restore the image, run the **Windows Preinstallation Environment(WinPE)** and the **Windows Recovery utility** will display. Follow these steps.

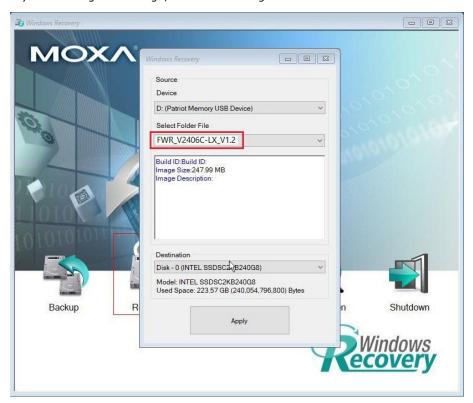
1. Click Recovery.



Select the Source USB Device, Image Folder File and check the image information, select the Destination Disk to restore. Click Apply.



3. If you are using Linux image, select Linux image to restore.



4. Click **Yes** to continue the process.



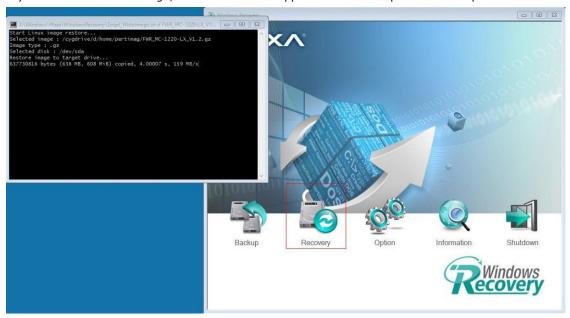
5. Click **Yes** to overwrite the destination drive.



6. Wait for the process to complete.



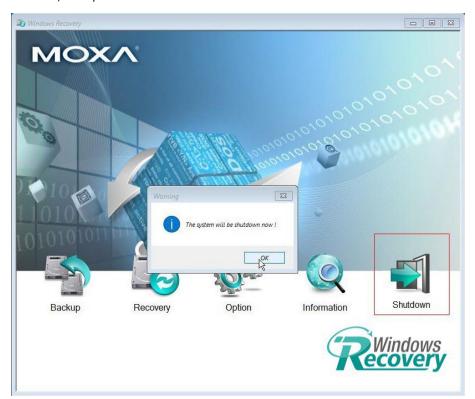
7. If you restore the Linux image, a new window will appear. Wait for the process to complete.



8. Click **OK**.



9. Click **OK**, the system will shut down and restart.



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NOTE

When you restart the computer, you will need to wait about 5 minutes for the computer to go through two cycles of the reboot process. The system configuration files will be initiated during the first boot-up process. Do not turn off or shut down the computer while the system is restarting.